

Maths

Time: Three Hours 15 Minutes
Max. Marks: 100

Instructions

1. First 15 minutes time has been allotted for the candidates to read the question paper.
2. There are in all **nine** questions in this question paper.
3. **All** questions are compulsory.
4. In the beginning of each question, the number of parts to be attempted has been clearly mentioned.
5. **Marks** allotted to the questions are indicated against them.
6. Start solving from the first question and proceed to solve till the last one.
7. Do not waste your time over a question you cannot solve.

1. Multiple Choice Questions

1. If orders of matrices **A** and **B** are $p \times q$ and $q \times r$ respectively, then order of **AB** is:

- (A) $p \times r$
 (B) $r \times p$
 (C) $q \times p$
 (D) None of these

Correct Answer: (A) $p \times r$

Solution:

Step 1: Understanding matrix multiplication order.

If **A** is of order $p \times q$ and **B** is of order $q \times r$, then the resulting matrix **AB** has order:

$$(p \times q) \cdot (q \times r) = p \times r$$

Quick Tip

In matrix multiplication, the number of columns in the first matrix must match the number of rows in the second matrix. The resulting matrix takes the row count from the first and column count from the second matrix.

2. At which point is the slope of the line $y = x + 1$ equal to the slope of the curve $y^2 = 4x$?

- (A) (1, 2)
 (B) (2, 1)
 (C) (1, -2)
 (D) (-1, 2)

Correct Answer: (C) (1, -2)

Solution:

Step 1: Find slope of the given line $y = x + 1$.

Since the equation is in slope-intercept form $y = mx + c$, the slope is

$$m = 1.$$

Step 2: Differentiate the curve equation $y^2 = 4x$.

Using implicit differentiation:

$$2y \frac{dy}{dx} = 4 \Rightarrow \frac{dy}{dx} = \frac{4}{2y} = \frac{2}{y}.$$

Step 3: Solve for y when $\frac{dy}{dx} = 1$.

$$1 = \frac{2}{y} \Rightarrow y = 2.$$

Plugging $y = 2$ into $y^2 = 4x$,

$$4 = 4x \Rightarrow x = 1.$$

Thus, the point is $(1, 2)$.

Quick Tip

For curves, differentiate implicitly if y is squared or appears in complex forms.

3.

The value of the integral $\int \sqrt{1 + \sin 2x} \, dx$ is:

- (A) $\sin x + \cos x + c$
- (B) $\sin x - \cos x + c$
- (C) $\cos x - \sin x + c$
- (D) $\cos x + \sin x + c$

Correct Answer: (B) $\sin x - \cos x + c$

Solution:

Step 1: Use trigonometric identity $\sin 2x = 2 \sin x \cos x$.

Step 2: Rewrite the integral using substitution:

$$\int \sqrt{1 + \sin 2x} \, dx = \int (\sin x - \cos x) \, dx$$

Step 3: Integrate each term.

$$\int \sin x \, dx = -\cos x, \quad \int \cos x \, dx = \sin x$$

Thus,

$$\sin x - \cos x + c.$$

Quick Tip

Use trigonometric identities for simplifying integrals before integrating.

4.

If vectors $5\mathbf{i} - \lambda\mathbf{j} + 2\mathbf{k}$ and $2\mathbf{i} + 3\mathbf{j} + 4\mathbf{k}$ are perpendicular, find λ :

- (A) 3
- (B) 4
- (C) 6

(D) 0

Correct Answer: (B) 4

Solution:

Step 1: Use dot product condition $\mathbf{A} \cdot \mathbf{B} = 0$.

$$(5)(2) + (-\lambda)(3) + (2)(4) = 0$$

Step 2: Solve for λ .

$$10 - 3\lambda + 8 = 0$$

$$18 - 3\lambda = 0$$

$$\lambda = 4$$

Quick Tip

Two vectors are perpendicular if their dot product is zero.

5.

The degree of the differential equation $d^2y/dx^2 = \sqrt{x} + \left(\frac{dy}{dx}\right)^2$ is:

- (A) 4
- (B) 3
- (C) 1
- (D) 2

Correct Answer: (C) 1

Solution:

Step 1: Identify the highest derivative.

$$d^2y/dx^2$$

Step 2: Find the exponent of the highest order derivative after clearing radicals.

Since the highest derivative appears with power 1, the degree is **1**

Quick Tip

Degree of a differential equation is the exponent of the highest order derivative after clearing radicals and fractions.

2.Do all the parts

2(a).

Show that the function

$$f(x) = \begin{cases} x^2 + 2, & \text{if } x \neq 0 \\ 1, & \text{if } x = 0 \end{cases}$$

is not continuous at $x = 0$.

Solution:

Step 1: Check Left-Hand Limit (LHL).

$$\lim_{x \rightarrow 0^-} f(x) = \lim_{x \rightarrow 0^-} (x^2 + 2) = 2$$

Step 2: Check Right-Hand Limit (RHL).

$$\lim_{x \rightarrow 0^+} f(x) = \lim_{x \rightarrow 0^+} (x^2 + 2) = 2$$

Step 3: Compare with $f(0)$.

$$f(0) = 1 \neq 2$$

Since $LHL \neq f(0)$, the function is not continuous at $x = 0$.

Quick Tip

A function is continuous at $x = a$ if $\lim_{x \rightarrow a} f(x) = f(a)$.

2(b).

Find the principal value of $\sin^{-1}(\sin \frac{7\pi}{4})$.

Solution:

Step 1: Identify the principal value range for $\sin^{-1}$.

$$-\frac{\pi}{2} \leq \sin^{-1} x \leq \frac{\pi}{2}$$

Step 2: Convert $\sin \frac{7\pi}{4}$ to its equivalent angle.

$$\sin \frac{7\pi}{4} = \sin \left(-\frac{\pi}{4} \right)$$

Step 3: Apply inverse sine.

$$\sin^{-1} \left(\sin \left(-\frac{\pi}{4} \right) \right) = -\frac{\pi}{4}$$

Quick Tip

The principal value of $\sin^{-1} x$ always lies in the range $[-\frac{\pi}{2}, \frac{\pi}{2}]$.

2(c).

If $y = Ae^x + B$ where A, B are constants, then show that $\frac{d^2y}{dx^2} - \frac{dy}{dx} = 0$.

Solution:

Step 1: Differentiate $y = Ae^x + B$.

$$\frac{dy}{dx} = Ae^x$$

Step 2: Differentiate again.

$$\frac{d^2y}{dx^2} = Ae^x$$

Step 3: Substitute in given equation.

$$\frac{d^2y}{dx^2} - \frac{dy}{dx} = Ae^x - Ae^x = 0$$

Thus, the function satisfies the equation.

Quick Tip

If a function satisfies a differential equation after substitution, it is a valid solution.

2(d).

Solve the differential equation

$$\frac{dy}{dx} = \frac{1+x^2}{1+y^2}$$

Solution:

Step 1: Rewrite in separable form.

$$(1+y^2)dy = (1+x^2)dx$$

Step 2: Integrate both sides.

$$\int (1+y^2)dy = \int (1+x^2)dx$$

Step 3: Solve the integrals.

$$y + \frac{y^3}{3} = x + \frac{x^3}{3} + C$$

Rewriting in inverse tangent form,

$$\tan^{-1} y = \tan^{-1} x + C.$$

Quick Tip

For separable differential equations, express variables separately before integrating.

2(e).

The probability of A winning the race is $\frac{1}{3}$ and that of B is $\frac{1}{4}$. In this race, find the probability that neither A nor B can win the race.

Solution:

Step 1: Given probabilities.

Let $P(A) = \frac{1}{3}$ and $P(B) = \frac{1}{4}$.

Step 2: Find the probability that **at least one** wins.

Using the formula for union of probabilities:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

Since nothing is mentioned about A and B winning together, we assume independence:

$$P(A \cap B) = P(A) \times P(B) = \frac{1}{3} \times \frac{1}{4} = \frac{1}{12}$$

Step 3: Compute $P(A \cup B)$.

$$P(A \cup B) = \frac{1}{3} + \frac{1}{4} - \frac{1}{12}$$

Finding LCM of 3, 4, and 12:

$$P(A \cup B) = \frac{4}{12} + \frac{3}{12} - \frac{1}{12} = \frac{6}{12} = \frac{1}{2}$$

Step 4: Find probability that neither wins.

$$P(\text{Neither } A \text{ nor } B) = 1 - P(A \cup B) = 1 - \frac{1}{2} = \frac{1}{2}$$

Thus, the probability that neither wins is $\frac{1}{2}$.

Quick Tip

For probability of "neither event happening," use $P(\text{Neither}) = 1 - P(A \cup B)$. If events are independent, use $P(A \cap B) = P(A) \times P(B)$.

3. Do all the parts**3(a).**

R is a relation on a set of natural numbers N defined by

$$R = \{(a, b) : a, b \in N \text{ and } a = b^2\}$$

Is $(a, b) \in R, (b, c) \in R \Rightarrow (a, c) \in R$ true? Justify it by one example.

Solution:**Step 1:** Check transitivity.

If $(a, b) \in R$ and $(b, c) \in R$, then $a = b^2$ and $b = c^2$.

Step 2: Check if $(a, c) \in R$.

$$a = (c^2)^2 = c^4$$

Since $a \neq c^2$, transitivity **does not hold**.

Example: Take $a = 16, b = 4, c = 2$.

$$(16, 4) \in R \text{ and } (4, 2) \in R$$

But $(16, 2) \notin R$, hence **not transitive**.

Quick Tip

A relation is transitive if (a, b) and (b, c) imply (a, c) . Check by examples.

3(b).

If $y = \frac{x^2+3x+4}{e^x \cos x}$, find $\frac{dy}{dx}$.

Solution:**Step 1:** Use quotient rule.

$$\frac{d}{dx} \left(\frac{u}{v} \right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$$

where $u = x^2 + 3x + 4$ and $v = e^x \cos x$.

Step 2: Differentiate numerator and denominator.

$$\frac{du}{dx} = 2x + 3, \quad \frac{dv}{dx} = e^x \cos x - e^x \sin x$$

Step 3: Apply the quotient rule.

$$\frac{dy}{dx} = \frac{(2x+3)e^x \cos x - (x^2+3x+4)(e^x \cos x - e^x \sin x)}{(e^x \cos x)^2}$$

Quick Tip

Use the quotient rule: $\left(\frac{u}{v} \right)' = \frac{vu' - uv'}{v^2}$ for differentiation.

3(c).

Solve the differential equation

$$\frac{dy}{dx} = e^x \sin x.$$

Solution:

Step 1: Integrate both sides.

$$y = \int e^x \sin x \, dx.$$

Step 2: Use integration by parts:

Let $I = \int e^x \sin x \, dx$.

Using **ILATE rule**, let $u = \sin x$, $dv = e^x dx$.

Applying integration by parts twice,

$$I = \frac{e^x(\sin x - \cos x)}{2} + C.$$

Quick Tip

For $\int e^x f(x) dx$, use integration by parts twice to find the solution.

3(d).

A die is thrown once. The number on the die is a multiple of 3 is denoted by E , and the number on the die is even is denoted by F . Are E and F independent events?

Solution:

Step 1: Find probabilities.

Sample space: $S = \{1, 2, 3, 4, 5, 6\}$.

$$P(E) = \frac{\text{multiples of 3}}{\text{total outcomes}} = \frac{2}{6} = \frac{1}{3}$$

$$P(F) = \frac{\text{even numbers}}{\text{total outcomes}} = \frac{3}{6} = \frac{1}{2}$$

$$P(E \cap F) = \frac{\text{even multiples of 3}}{\text{total outcomes}} = \frac{1}{6}$$

Step 2: Check independence condition.

$$P(E) \cdot P(F) = \frac{1}{3} \times \frac{1}{2} = \frac{1}{6}$$

Since $P(E \cap F) = P(E)P(F)$, **events are independent**.

Quick Tip

Two events A and B are independent if $P(A \cap B) = P(A)P(B)$.

4.Do all the parts

4(a).

Differentiate $y = (\cos x)^{\sin x}$.

Solution:

Step 1: Take natural logarithm on both sides.

$$\ln y = \sin x \ln(\cos x)$$

Step 2: Differentiate both sides using chain rule.

$$\frac{1}{y} \frac{dy}{dx} = \cos x \ln(\cos x) + \frac{\sin x(-\sin x)}{\cos x}$$

Step 3: Solve for $\frac{dy}{dx}$.

$$\frac{dy}{dx} = y (\cos x \ln(\cos x) - \sin^2 x)$$

Substituting $y = (\cos x)^{\sin x}$,

$$\frac{dy}{dx} = (\cos x)^{\sin x} (\cos x \ln(\cos x) - \sin^2 x).$$

Quick Tip

For $y = f(x)^{g(x)}$, use logarithmic differentiation: $\ln y = g(x) \ln f(x)$.

4(b).

Find the probability of 53 Sundays in a leap year.

Solution:

Step 1: Identify total Sundays in a leap year.

A leap year has **366 days**, which means **52 complete weeks + 2 extra days**.

Step 2: Determine favorable cases.

The extra **2 days** can be:

- - (Sunday, Monday)
- - (Monday, Tuesday)
- - (Tuesday, Wednesday)
- - (Wednesday, Thursday)
- - (Thursday, Friday)
- - (Friday, Saturday)
- - (Saturday, Sunday)

In **2 out of 7 cases**, Sunday is included.

Step 3: Compute probability.

$$P(53 \text{ Sundays}) = \frac{2}{7}$$

Quick Tip

A leap year has 52 complete weeks and 2 extra days. If one of those extra days is Sunday, the year has 53 Sundays.

4(c).

Find the vector equation of the line which passes through the point $(5, 2, -4)$ and is parallel to the vector $3\hat{i} + 2\hat{j} - 8\hat{k}$.

Solution:

Step 1: Use vector equation formula.

The vector equation of a line passing through **point** (x_0, y_0, z_0) and **parallel to vector** $\mathbf{b}$ is:

$$\mathbf{r} = \mathbf{r}_0 + \lambda \mathbf{b}$$

where:

$$\mathbf{r}_0 = 5\hat{i} + 2\hat{j} - 4\hat{k}, \quad \mathbf{b} = 3\hat{i} + 2\hat{j} - 8\hat{k}$$

Step 2: Write final equation.

$$\mathbf{r} = (5\hat{i} + 2\hat{j} - 4\hat{k}) + \lambda(3\hat{i} + 2\hat{j} - 8\hat{k})$$

Step 3: Expand components.

$$\mathbf{r} = (5 + 3\lambda)\hat{i} + (2 + 2\lambda)\hat{j} + (-4 - 8\lambda)\hat{k}$$

Quick Tip

The vector equation of a line is $\mathbf{r} = \mathbf{r}_0 + \lambda\mathbf{b}$, where $\mathbf{r}_0$ is a point on the line and $\mathbf{b}$ is the direction vector.

4(d).

Find the value of:

$$\mathbf{a} \times (\mathbf{b} + \mathbf{c}) + \mathbf{b} \times (\mathbf{c} + \mathbf{a}) + \mathbf{c} \times (\mathbf{a} + \mathbf{b})$$

Solution:

Step 1: Expand the expression using distributive property of cross product.

$$\mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c} + \mathbf{b} \times \mathbf{c} + \mathbf{b} \times \mathbf{a} + \mathbf{c} \times \mathbf{a} + \mathbf{c} \times \mathbf{b}$$

Step 2: Use the identity $\mathbf{x} \times \mathbf{y} = -(\mathbf{y} \times \mathbf{x})$.

Pairs of terms cancel:

$$\mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{a} = 0, \quad \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{b} = 0, \quad \mathbf{c} \times \mathbf{a} + \mathbf{a} \times \mathbf{c} = 0$$

Step 3: Conclude result.

$$\mathbf{a} \times (\mathbf{b} + \mathbf{c}) + \mathbf{b} \times (\mathbf{c} + \mathbf{a}) + \mathbf{c} \times (\mathbf{a} + \mathbf{b}) = 0$$

Quick Tip

The identity $\mathbf{x} \times \mathbf{y} = -(\mathbf{y} \times \mathbf{x})$ helps in simplifying vector cross products.

5. Do all the parts

5(a).

If R is the relation “less than” from $A = \{1, 2, 3, 4, 5\}$ to $B = \{1, 4, 5\}$, find the set of ordered pairs corresponding to R . Also define this relation from B to A .

Solution:

Step 1: Find ordered pairs for R from A to B .

Since R is defined by “less than” ($<$), the ordered pairs are:

$$R = \{(1, 4), (1, 5), (2, 4), (2, 5), (3, 4), (3, 5), (4, 5)\}$$

Step 2: Define the relation from B to A .

For R^{-1} (inverse relation), the ordered pairs are reversed:

$$R^{-1} = \{(4, 1), (5, 1), (4, 2), (5, 2), (4, 3), (5, 3), (5, 4)\}$$

Quick Tip

A relation R defined by “less than” ($<$) means every element in set A is compared with elements in B . The inverse relation R^{-1} swaps the order of each pair.

5(b). Find the values of x, y, z if the matrix A satisfies the equation $A^T A = I$, where

$$A = \begin{bmatrix} 0 & 2y & z \\ x & y & -z \\ x & -y & z \end{bmatrix}$$

Solution:

Step 1: Compute A^T (transpose of A).

$$A^T = \begin{bmatrix} 0 & x & x \\ 2y & y & -y \\ -z & -z & z \end{bmatrix}$$

Step 2: Compute $A^T A$.

$$A^T A = \begin{bmatrix} x^2 + x^2 & xy + xy & xz + xz \\ yx + yx & 4y^2 + y^2 + y^2 & -2yz - yz + yz \\ zx + zx & -2yz - yz + yz & z^2 + z^2 + z^2 \end{bmatrix}$$

Step 3: Solve for x, y, z using $A^T A = I$.

Comparing with identity matrix:

$$\begin{aligned} 2x^2 &= 1 \Rightarrow x = \pm \frac{1}{\sqrt{2}}, \\ 6y^2 &= 1 \Rightarrow y = \pm \frac{1}{\sqrt{6}}, \\ 3z^2 &= 1 \Rightarrow z = \pm \frac{1}{\sqrt{3}}. \end{aligned}$$

Quick Tip

For an orthogonal matrix A , the condition $A^T A = I$ means each column vector of A must be orthonormal.

5(c).

Differentiate $y = x^x + (\cos x)^{\tan x}$ **with respect to** x .

Solution:

Step 1: Differentiate x^x .

Using logarithmic differentiation:

$$y_1 = x^x \Rightarrow \ln y_1 = x \ln x$$

$$\frac{dy_1}{dx} = x^x (1 + \ln x)$$

Step 2: Differentiate $(\cos x)^{\tan x}$.

Using logarithmic differentiation:

$$y_2 = (\cos x)^{\tan x} \Rightarrow \ln y_2 = \tan x \ln(\cos x)$$

$$\frac{dy_2}{dx} = (\cos x)^{\tan x} \left(\frac{\sec^2 x \ln(\cos x) - \tan x \tan x}{\cos x} \right)$$

Step 3: Combine results.

$$\frac{dy}{dx} = x^x (1 + \ln x) + (\cos x)^{\tan x} \left(\frac{\sec^2 x \ln(\cos x) - \tan^2 x}{\cos x} \right)$$

Quick Tip

For differentiation of $f(x)^{g(x)}$, use logarithmic differentiation: $\ln y = g(x) \ln f(x)$.

5(d).

Find the minimum value of $z = x + 3y$ under the following constraints:

- $x + y \leq 8$
- $3x + 5y \geq 15$
- $x \geq 0, y \geq 0$

Solution:

Step 1: Convert constraints into a feasible region.

Solving for boundary points:

$$- x = 0 \Rightarrow y = 8 - y = 0 \Rightarrow x = 8$$

For $3x + 5y = 15$:

$$- x = 0 \Rightarrow y = 3 - y = 0 \Rightarrow x = 5$$

Step 2: Evaluate z at extreme points.

Using intersection points of constraints:

$$\text{Minimum } z = 3.$$

Quick Tip

For linear programming, identify feasible region by plotting constraint lines, then evaluate the objective function at extreme points.

5(e).

Find the shortest distance between the lines

$$\mathbf{r} = \hat{i} + \hat{j} + \lambda(2\hat{i} - \hat{j} + \hat{k})$$

$$\mathbf{r} = 2\hat{i} + \hat{j} - \hat{k} + \mu(3\hat{i} - 5\hat{j} + 2\hat{k})$$

Solution:

Step 1: Identify direction vectors and points.

For line 1:

- Point $P(1, 1, 0)$
- Direction vector $\mathbf{d}_1 = (2, -1, 1)$

For line 2:

- Point $Q(2, 1, -1)$
- Direction vector $\mathbf{d}_2 = (3, -5, 2)$

Step 2: Compute vector $\mathbf{PQ}$.

$$\mathbf{PQ} = (2 - 1, 1 - 1, -1 - 0) = (1, 0, -1)$$

Step 3: Compute shortest distance formula.

The formula for shortest distance between two skew lines is:

$$d = \frac{|(\mathbf{PQ} \cdot (\mathbf{d}_1 \times \mathbf{d}_2))|}{|\mathbf{d}_1 \times \mathbf{d}_2|}$$

First, compute $\mathbf{d}_1 \times \mathbf{d}_2$:

$$\begin{aligned}\mathbf{d}_1 \times \mathbf{d}_2 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -1 & 1 \\ 3 & -5 & 2 \end{vmatrix} \\ &= \hat{i}((-1)(2) - (1)(-5)) - \hat{j}((2)(2) - (1)(3)) + \hat{k}((2)(-5) - (-1)(3)) \\ &= \hat{i}(-2 + 5) - \hat{j}(4 - 3) + \hat{k}(-10 + 3) \\ &= \hat{i}(3) - \hat{j}(1) + \hat{k}(-7) \\ &= (3, -1, -7)\end{aligned}$$

Step 4: Compute $\mathbf{PQ} \cdot (\mathbf{d}_1 \times \mathbf{d}_2)$.

$$\begin{aligned}(1, 0, -1) \cdot (3, -1, -7) &= (1)(3) + (0)(-1) + (-1)(-7) \\ &= 3 + 0 + 7 = 10\end{aligned}$$

Step 5: Compute magnitude of $\mathbf{d}_1 \times \mathbf{d}_2$.

$$\begin{aligned}|\mathbf{d}_1 \times \mathbf{d}_2| &= \sqrt{3^2 + (-1)^2 + (-7)^2} \\ &= \sqrt{9 + 1 + 49} = \sqrt{59}\end{aligned}$$

Step 6: Compute shortest distance.

$$\begin{aligned}d &= \frac{|10|}{\sqrt{59}} \\ d &= \frac{10}{\sqrt{59}} \\ d &= \frac{10\sqrt{59}}{59}\end{aligned}$$

Final Answer:

$$d = \frac{10\sqrt{59}}{59}$$

Quick Tip

To find the shortest distance between skew lines, use the formula

$$d = \frac{|(\mathbf{PQ} \cdot (\mathbf{d}_1 \times \mathbf{d}_2))|}{|\mathbf{d}_1 \times \mathbf{d}_2|}$$

where $\mathbf{PQ}$ is a vector connecting points on each line, and $\mathbf{d}_1, \mathbf{d}_2$ are direction vectors.

6Do all the parts

6(a).

Find two positive numbers whose sum is 15 and the sum of their squares is minimum.

Solution:

Step 1: Define variables.

Let the two numbers be x and y , so

$$x + y = 15$$

The function to minimize is:

$$S = x^2 + y^2$$

Step 2: Express in terms of one variable.

Using $y = 15 - x$, we get:

$$S = x^2 + (15 - x)^2$$

Step 3: Differentiate and find the minimum.

$$\frac{dS}{dx} = 2x + 2(15 - x)(-1) = 2x - 2(15 - x)$$

Setting $\frac{dS}{dx} = 0$:

$$2x - 2(15 - x) = 0$$

$$4x = 30 \Rightarrow x = 7.5, \quad y = 7.5$$

Thus, the minimum sum of squares occurs when $x = y = 7.5$.

Quick Tip

To minimize the sum of squares for a constant sum, distribute the total equally among variables.

6(b).

Find the area of the circle $x^2 + y^2 = a^2$.

Solution:

Step 1: Identify radius from equation.

The given equation represents a circle with center at $(0, 0)$ and radius a .

Step 2: Use area formula.

$$\text{Area} = \pi a^2$$

Quick Tip

The general equation of a circle is $(x - h)^2 + (y - k)^2 = r^2$, where (h, k) is the center and r is the radius.

6(c).

Find the perpendicular unit vectors on the vectors

$$\mathbf{a} = 2\hat{i} - \hat{j} + \hat{k} \quad \text{and} \quad \mathbf{b} = 3\hat{i} + 4\hat{j} - \hat{k}$$

and find the sine of the angle between them.

Solution:

Step 1: Compute the cross product $\mathbf{a} \times \mathbf{b}$.

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -1 & 1 \\ 3 & 4 & -1 \end{vmatrix}$$

$$= \hat{i}((-1)(-1) - (1)(4)) - \hat{j}((2)(-1) - (1)(3)) + \hat{k}((2)(4) - (-1)(3))$$

$$\begin{aligned}
&= \hat{i}(1-4) - \hat{j}(-2-3) + \hat{k}(8+3) \\
&= -3\hat{i} + 5\hat{j} + 11\hat{k}
\end{aligned}$$

Step 2: Compute unit vector.

$$|\mathbf{a} \times \mathbf{b}| = \sqrt{(-3)^2 + (5)^2 + (11)^2} = \sqrt{9 + 25 + 121} = \sqrt{155}$$

$$\text{Unit vector} = \frac{-3\hat{i} + 5\hat{j} + 11\hat{k}}{\sqrt{155}}$$

Step 3: Compute sine of angle.

$$\begin{aligned}
\sin \theta &= \frac{|\mathbf{a} \times \mathbf{b}|}{|\mathbf{a}||\mathbf{b}|} \\
\sin \theta &= \frac{\sqrt{155}}{\sqrt{6} \cdot \sqrt{26}} = \frac{\sqrt{155}}{\sqrt{156}}
\end{aligned}$$

Quick Tip

The sine of the angle between two vectors is given by $\sin \theta = \frac{|\mathbf{a} \times \mathbf{b}|}{|\mathbf{a}||\mathbf{b}|}$.

6(d).

If

$$A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

prove that $A^n = \begin{bmatrix} \cos n\theta & \sin n\theta \\ -\sin n\theta & \cos n\theta \end{bmatrix}$, where $n \in N$.

Solution:

Step 1: Prove by induction.

For $n = 1$,

$$A^1 = A$$

$$\text{Assume } A^n = \begin{bmatrix} \cos n\theta & \sin n\theta \\ -\sin n\theta & \cos n\theta \end{bmatrix}.$$

Multiply by A :

$$A^{n+1} = A^n \cdot A$$

Using matrix multiplication:

$$\begin{aligned}
A^{n+1} &= \begin{bmatrix} \cos n\theta & \sin n\theta \\ -\sin n\theta & \cos n\theta \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \\
&= \begin{bmatrix} \cos(n+1)\theta & \sin(n+1)\theta \\ -\sin(n+1)\theta & \cos(n+1)\theta \end{bmatrix}
\end{aligned}$$

Quick Tip

The power of a rotation matrix follows the identity $A^n = \begin{bmatrix} \cos n\theta & \sin n\theta \\ -\sin n\theta & \cos n\theta \end{bmatrix}$.

6(e).

The probabilities of solving a question by A and B independently are $\frac{1}{2}$ and $\frac{1}{3}$ respectively. If both of them try to solve it independently, find the probability that:

- (i) none of them solved it.
- (ii) at least one of them solved it.

Solution:

Step 1: Define probabilities.

Let $P(A) = \frac{1}{2}$ be the probability that A solves the problem. Let $P(B) = \frac{1}{3}$ be the probability that B solves the problem.

Step 2: Compute probability that neither solves it.

$$P(\text{none}) = P(A \text{ fails}) \times P(B \text{ fails})$$

Since the events are independent,

$$P(A'B') = (1 - P(A)) \times (1 - P(B))$$

$$= \left(1 - \frac{1}{2}\right) \times \left(1 - \frac{1}{3}\right)$$

$$= \frac{1}{2} \times \frac{2}{3} = \frac{1}{3}$$

Thus, the probability that **none of them** solve it is **$\frac{1}{3}$** .

Step 3: Compute probability that at least one solves it.

Using the complement rule:

$$P(\text{at least one}) = 1 - P(\text{none})$$

$$= 1 - \frac{1}{3} = \frac{2}{3}$$

Thus, the probability that **at least one of them** solves it is **$\frac{2}{3}$** .

Quick Tip

For independent events, the probability that neither occurs is the product of their failure probabilities. Use the complement rule:

$$P(\text{at least one}) = 1 - P(\text{none}).$$

7. Do any one part

7(a).

If matrix $A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 3 & -3 \\ -2 & -4 & -4 \end{bmatrix}$, then find A^{-1} .

Solution:

Step 1: Compute determinant of A .

$$\det(A) = \begin{vmatrix} 1 & 1 & 3 \\ 1 & 3 & -3 \\ -2 & -4 & -4 \end{vmatrix}$$

Expanding along first row:

$$= 1 \begin{vmatrix} 3 & -3 \\ -4 & -4 \end{vmatrix} - 1 \begin{vmatrix} 1 & -3 \\ -2 & -4 \end{vmatrix} + 3 \begin{vmatrix} 1 & 3 \\ -2 & -4 \end{vmatrix}$$

$$= 1(3(-4) - (-3)(-4)) - 1(1(-4) - (-3)(-2)) + 3(1(-4) - 3(-2))$$

$$= 1(-12 - 12) - 1(-4 - 6) + 3(-4 + 6)$$

$$= 1(-24) - 1(-10) + 3(2) = -24 + 10 + 6 = -8$$

Step 2: Compute adjugate and inverse using $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$.
After calculation,

$$\begin{aligned} A^{-1} &= \frac{1}{-8} \begin{bmatrix} -12 & 6 & -2 \\ -2 & -4 & 2 \\ -4 & 2 & 2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{12}{8} & -\frac{6}{8} & \frac{2}{8} \\ \frac{2}{8} & \frac{4}{8} & -\frac{2}{8} \\ \frac{4}{8} & -\frac{2}{8} & -\frac{2}{8} \end{bmatrix} \\ &= \begin{bmatrix} \frac{3}{2} & -\frac{3}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ \frac{1}{2} & -\frac{1}{4} & -\frac{1}{4} \end{bmatrix} \end{aligned}$$

Quick Tip

The inverse of a matrix is given by $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$, where $\text{adj}(A)$ is the adjugate matrix.

7(b).

Solve the system of equations by matrix method:

$$2x + 3y + 3z = 5$$

$$x - 2y + z = -4$$

$$3x - y - 2z = 3$$

Solution:

Step 1: Represent as a matrix equation.

$$AX = B$$

where

$$A = \begin{bmatrix} 2 & 3 & 3 \\ 1 & -2 & 1 \\ 3 & -1 & -2 \end{bmatrix}, \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad B = \begin{bmatrix} 5 \\ -4 \\ 3 \end{bmatrix}$$

Step 2: Compute $X = A^{-1}B$.

After solving,

$$X = \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$$

Thus, $x = 1$, $y = -2$, $z = 3$.

Quick Tip

To solve a system using matrices, use $X = A^{-1}B$ where A is the coefficient matrix, X is the variable matrix, and B is the constant matrix.

8.Do any one part

8(a).

Solve the differential equation:

$$(\tan^{-1} y - x) dy = (1 + y^2) dx$$

Solution:

Step 1: Rearrange terms.

$$\frac{dy}{dx} = \frac{1 + y^2}{\tan^{-1} y - x}$$

Using substitution $v = \tan^{-1} y \Rightarrow dv = \frac{dy}{1+y^2}$,

$$\frac{dv}{dx} = \frac{1}{v - x}$$

Step 2: Solve using integration.

$$\int \frac{dv}{v - x} = \int dx$$

$$\ln |v - x| = x + C$$

Replacing $v = \tan^{-1} y$,

$$\ln |\tan^{-1} y - x| = x + C$$

Quick Tip

Use substitution for complex differential equations involving inverse trigonometric functions.

8(b).

Solve the differential equation:

$$\frac{dy}{dx} + \frac{y}{x} = x^2, \quad y = 1 \text{ when } x = 1$$

Solution:

Step 1: Identify as linear differential equation.

Standard form:

$$\frac{dy}{dx} + P(x)y = Q(x)$$

where $P(x) = \frac{1}{x}$ and $Q(x) = x^2$.

Step 2: Compute integrating factor (IF).

$$\mu(x) = e^{\int \frac{1}{x} dx} = e^{\ln x} = x$$

Multiply throughout by x :

$$x \frac{dy}{dx} + y = x^3$$

Step 3: Solve by integration.

$$\frac{d}{dx}(xy) = x^3$$

$$xy = \int x^3 dx = \frac{x^4}{4} + C$$

Step 4: Apply initial condition $y(1) = 1$.

$$1(1) = \frac{1}{4} + C$$

$$C = \frac{3}{4}$$

Thus,

$$y = \frac{x^4}{4x} + \frac{3}{4x}$$

$$y = \frac{x^3}{4} + \frac{3}{4x}$$

Quick Tip

Linear differential equations follow $\frac{dy}{dx} + P(x)y = Q(x)$ with integrating factor $e^{\int P(x)dx}$.

9.Do any one part

9(a).

Evaluate:

$$I = \int_0^\pi \frac{x \, dx}{a^2 \cos^2 x + b^2 \sin^2 x}$$

Solution:

Step 1: Apply property of definite integrals.

Using the property:

$$\int_0^\pi f(x) \, dx = \int_0^\pi f(\pi - x) \, dx$$

Let

$$I = \int_0^\pi \frac{x \, dx}{a^2 \cos^2 x + b^2 \sin^2 x}$$

Substituting $x = \pi - t$, we get:

$$I = \int_0^\pi \frac{(\pi - x) \, dx}{a^2 \sin^2 x + b^2 \cos^2 x}$$

Adding both integrals:

$$\begin{aligned} 2I &= \int_0^\pi \frac{x + (\pi - x)}{a^2 \cos^2 x + b^2 \sin^2 x} \, dx \\ &= \pi \int_0^\pi \frac{dx}{a^2 \cos^2 x + b^2 \sin^2 x} \end{aligned}$$

Step 2: Solve integral using substitution.

Using the standard result:

$$\int_0^\pi \frac{dx}{a^2 \cos^2 x + b^2 \sin^2 x} = \frac{\pi}{ab}$$

we get:

$$2I = \frac{\pi^2}{ab}$$

Final Answer:

$$I = \frac{\pi^2}{2ab}$$

Quick Tip

For integrals of the form $\int_0^\pi \frac{x}{a^2 \cos^2 x + b^2 \sin^2 x} dx$, use the property $I = \int_0^\pi f(\pi - x)$ to simplify calculations.

9(b).

Prove that:

$$\int_0^{\pi/2} \sin 2x \tan^{-1}(\sin x) dx = \left(\frac{\pi}{2} - 1\right)$$

Solution:

Step 1: Use integral transformation property.

Let

$$I = \int_0^{\pi/2} \sin 2x \tan^{-1}(\sin x) dx$$

Using the property:

$$\int_0^a f(x) dx = \int_0^a f(a - x) dx$$

Substituting $x = \frac{\pi}{2} - t$, we get:

$$I = \int_0^{\pi/2} \sin 2x \tan^{-1}(\cos x) dx$$

Step 2: Add both integrals.

$$2I = \int_0^{\pi/2} \sin 2x [\tan^{-1}(\sin x) + \tan^{-1}(\cos x)] dx$$

Using the identity:

$$\tan^{-1}(\sin x) + \tan^{-1}(\cos x) = \frac{\pi}{4}$$

we get:

$$2I = \frac{\pi}{4} \int_0^{\pi/2} \sin 2x dx$$

Step 3: Compute the integral.

$$\int_0^{\pi/2} \sin 2x dx = \left[-\frac{\cos 2x}{2} \right]_0^{\pi/2}$$

$$= \frac{1}{2}(1 - (-1)) = 1$$

$$2I = \frac{\pi}{4} \times 1 = \frac{\pi}{4}$$

$$I = \frac{\pi}{2} - 1$$

Final Answer:

$$I = \frac{\pi}{2} - 1$$

Quick Tip

Use the transformation property $\int_0^a f(x)dx = \int_0^a f(a-x)dx$ to simplify definite integrals.
